

# Phenotypic selection: elaborations

Michael Morrissey  
February 3, 2020



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## Preliminaries

My goals

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    - ▶ erroneous estimates of selection
    - ▶ assessing genetic associations between traits and fitness

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    - ▶ interpreting all those  $\gamma$  terms

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  2. Missing variable problems
    - ▶ erroneous estimates of selection
    - ▶ assessing genetic associations between traits and fitness
  3. A closer look at non-linear selection
    - ▶ interpreting all those  $\gamma$  terms
  4. Does the selection gradient measure what we really want?
    - ▶ what traits are materially relevant to fitness?

# The additive partition of $S$

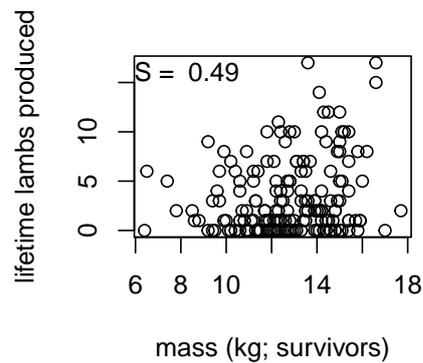
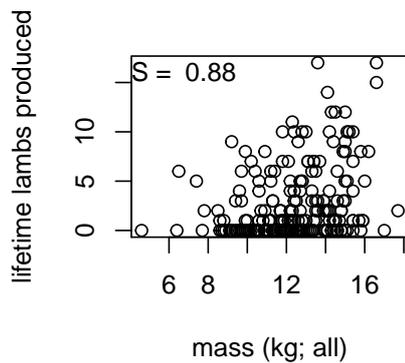
The total selection differential over  $k$  episodes is

$$S_T = \sum_j^k S_j$$

- ▶ From before,  $S_1 = 0.39$  kg.
- ▶ Among survivors of the first winter, subsequent selection is  $S_2 = 0.49$  kg.

So,

$$S = S_1 + S_2 = 0.88 \text{ kg}$$



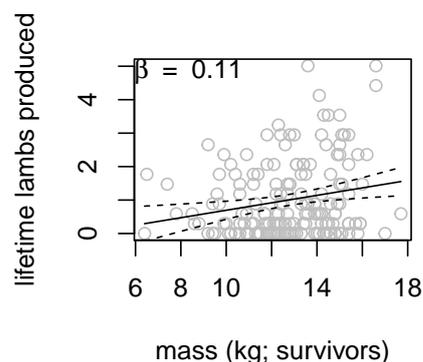
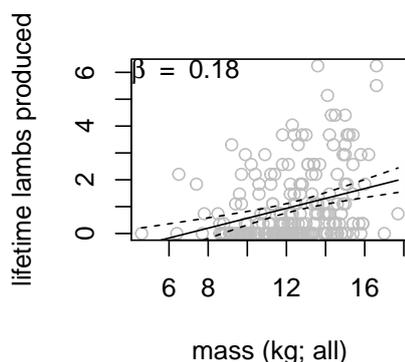
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# The additive partition of $\beta$

The total selection gradient over  $k$  episodes is

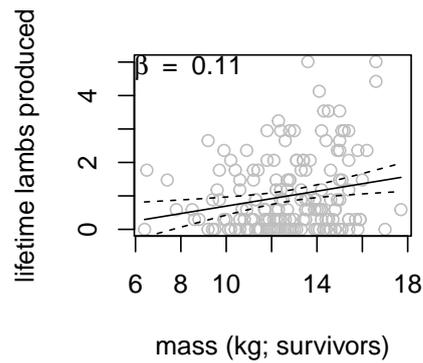
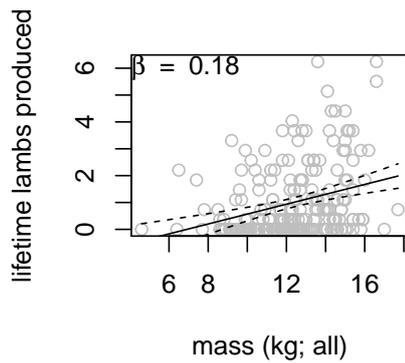
$$\beta_T = \sum_{j=1}^k \frac{\sigma_{j-1}^2}{\sigma_0^2} \beta_j$$

- ▶ this is a weighted additive partitioning of selection gradients.
- ▶ since viability selection changes the variance, and the variance is in the denominator of the formula for  $\beta$ , this change must be taken into account.



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# $\beta_T$ for body mass

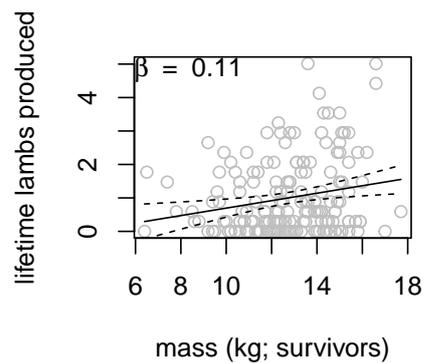
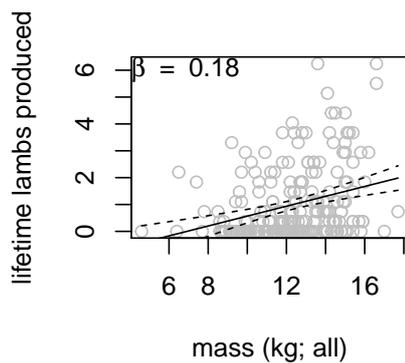


$$\beta_1 = 0.082, \beta_2 = 0.111, \beta = 0.184$$

$$V_0 = 4.78, V_1 = 4.38$$



# $\beta_T$ for body mass



$$\beta_1 = 0.082, \beta_2 = 0.111, \beta = 0.184$$

$$V_0 = 4.78, V_1 = 4.38$$

$$\beta = \beta_1 + \frac{V_1}{V_0}\beta_2 = 0.082 + \frac{4.38}{4.78}0.111 = 0.184$$



# Is it worth partitioning selection?

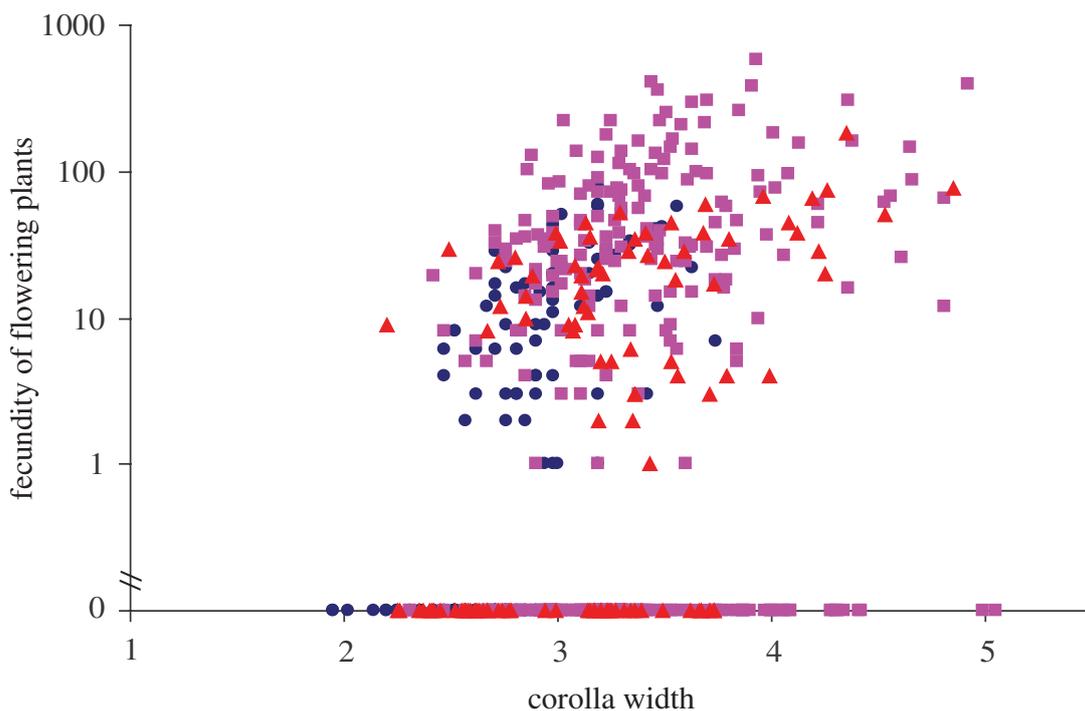
If you have lifetime fitness, why break it down?

- ▶ It is worth knowing where in the life cycle selection arises
- ▶ It is statistically equally powerful, despite more stuff being calculated.

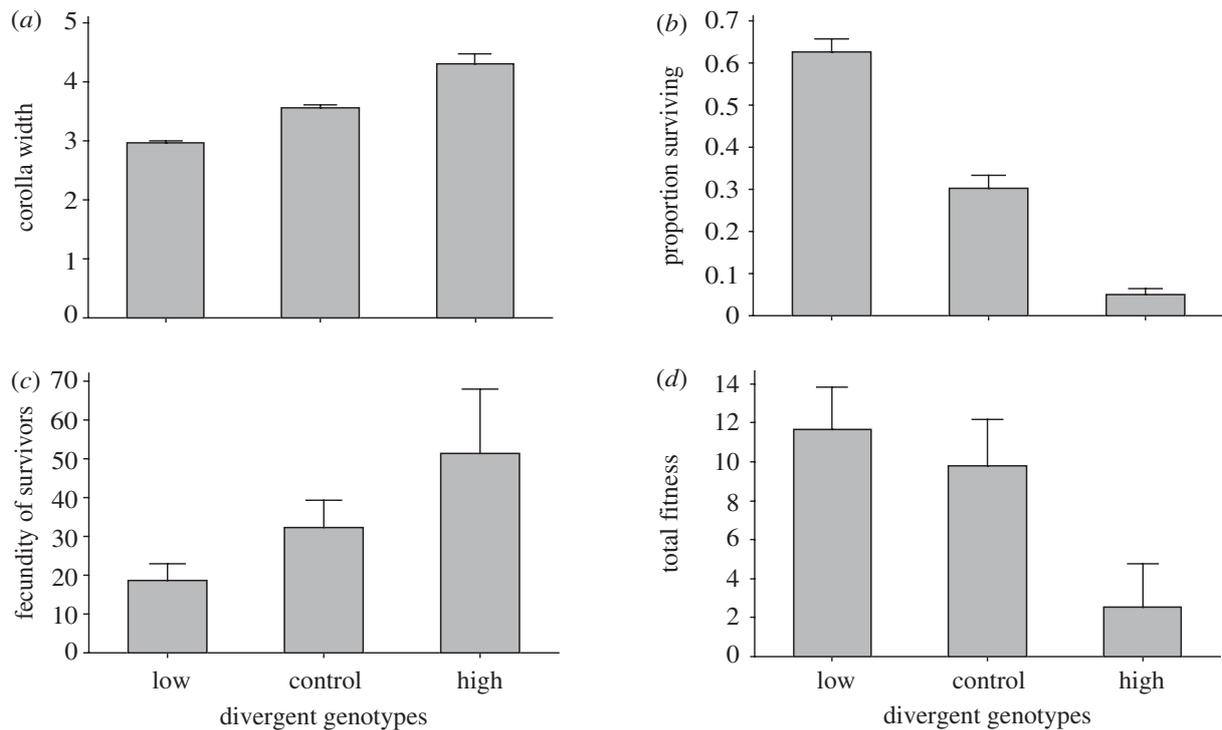
for e.g., episodes of selection analysis for lamb mass:

gradient	estimate	standard error
$S_1$	0.394	0.091
$S_1$	0.488	0.183
$S_{total}$	0.881	0.215
$S_1 + S_1$	0.881	0.201

## What about missing episodes of selection?



# What about missing episodes of selection?

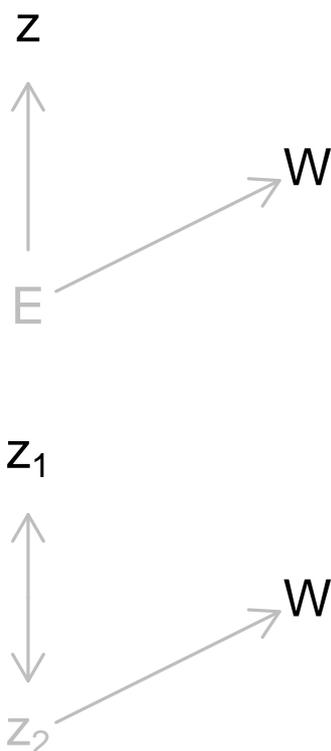


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## Missing traits



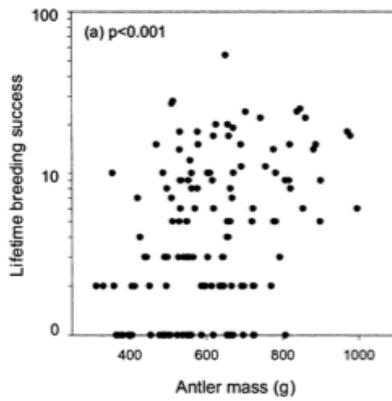
- ▶ Any trait or environmental variable that causes trait-fitness covariance will leave a mistaken signature of selection.
- ▶ Solution (part): do more multivariate analyses.
- ▶ Solution (other part): include environmental variables in regression-based selection analyses.
- ▶ This has been considered and prematurely rejected.

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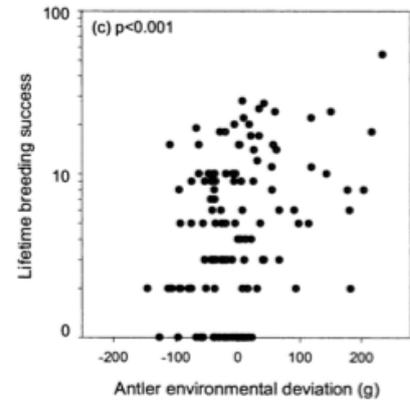
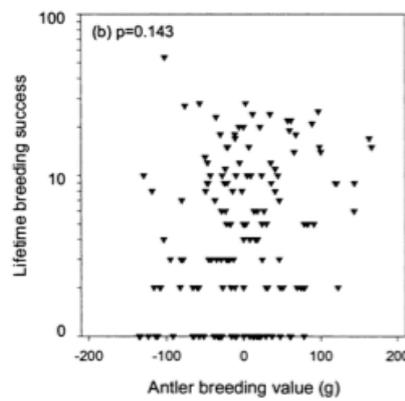
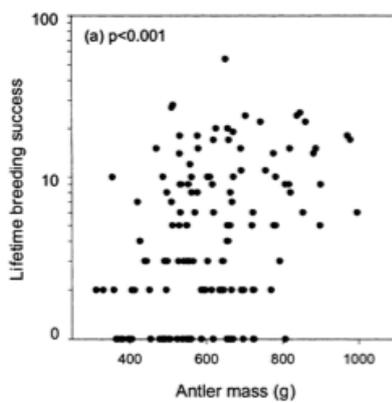
# Signatures of missing traits: red deer



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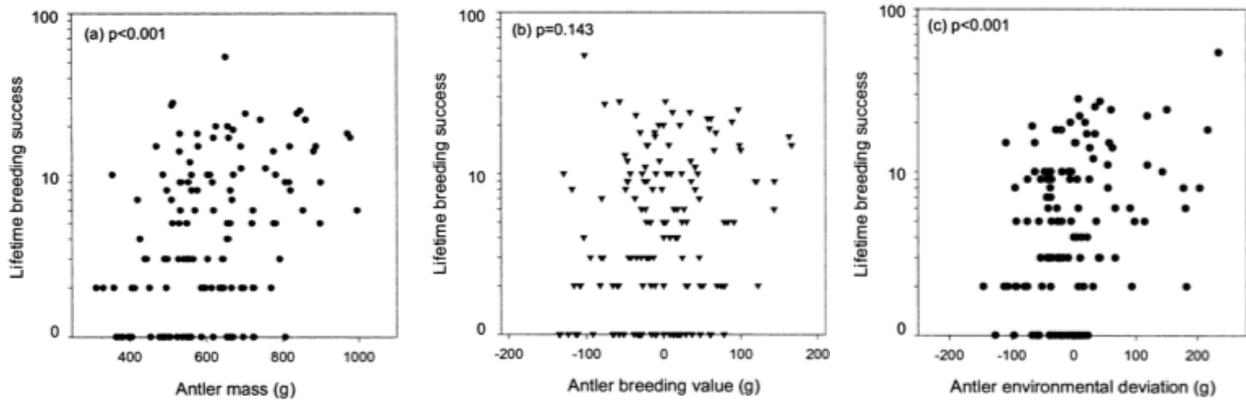
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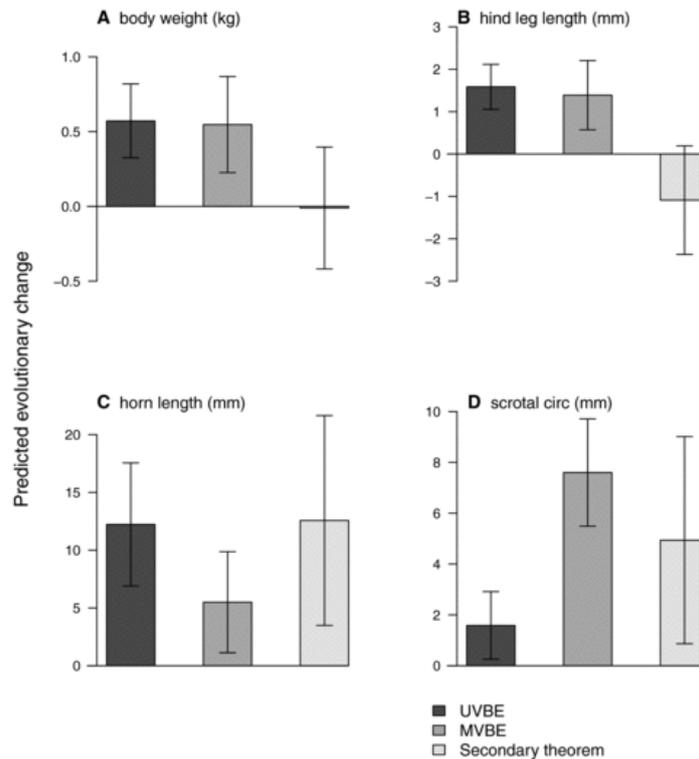


This amounts to applying the secondary theorem of selection

$$E[\Delta \bar{z}] = E[\Delta \bar{a}] = \sigma_{a,w}$$

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# Signatures of missing traits: Soay sheep



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# Empirical application of the STS without stats-on-stats

## 1

The secondary theorem (Robertson-Price equation applied to breeding values) is

$$\Delta \bar{z} = \sigma_a(z, w)$$

and the breeder's equation is

$$\Delta \bar{z} = h^2 \sigma_p(z, w)$$

Set these to be equal:

$$\sigma_a(z, w) = \frac{\sigma_a^2(z)}{\sigma_p^2(z)} \sigma_p(z, w)$$

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$$\frac{\sigma_a(z, w)}{\sigma_a^2(z)} = \frac{\sigma_p(z, w)}{\sigma_p^2(z)}$$

$$\beta_a = \beta$$

The condition for the breeder's (Lande) equation to be predictive, namely equality of genetic and phenotypic (partial) regressions of traits on fitness, can be decomposed further:

$$\frac{\sigma_a(z, w)}{\sigma_a^2(z)} = \frac{\sigma_p(z, w)}{\sigma_p^2(z)}$$

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$$\frac{\sigma_a(z, w)}{\sigma_a^2(z)} = \frac{\sigma_p(z, w)}{\sigma_p^2(z)}$$

$$\frac{\sigma_a(z, w)}{\sigma_a^2(z)} = \frac{\sigma_a(z, w) + \sigma_e(z, w)}{\sigma_a^2(z) + \sigma_e^2(z)}$$

$$\frac{\sigma_a(z, w)}{\sigma_a^2(z)} = \frac{\sigma_e(z, w)}{\sigma_e^2(z)}$$

Thus, a corollary of the condition  $\beta_a = \beta$ ,  $\beta_a = \beta_e$   
 The numerators and denominators of  $\beta$ ,  $\beta_a$  and  $\beta_e$  are all estimable by multi-response mixed model methods.

# LMM and GLMM analysis of the STS and associated relationships

GLMM analysis seems most natural:

$$\begin{bmatrix} z_i \\ \log(E[W])_i \end{bmatrix} = \mathbf{X}\beta + \begin{bmatrix} a_{z,i} \\ a_{W,i} \end{bmatrix} + \dots$$

Where  $\mathbf{a}_i$ , and especially their covariance, is estimated using the pedigree.

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Where  $\mathbf{a}_i$ , and especially their covariance, is estimated using the pedigree. But what matters is relative fitness on the scale upon which it is expressed... ..but it turns out that the log-link GLMM has a cool justification:

$$x_i = \log(E[W]_i)$$

FTNS analogue:

$$\Delta\bar{w} = e^{\sigma_a^2(x)} - 1$$

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$$x_i = \log(E[W]_i)$$

FTNS analogue:

$$\Delta\bar{w} = e^{\sigma_a^2(x)} - 1$$

STS analogue:

$$\Delta\bar{z} = \sigma_a^2(z, x)$$

So, the GLMM consistency measure is:

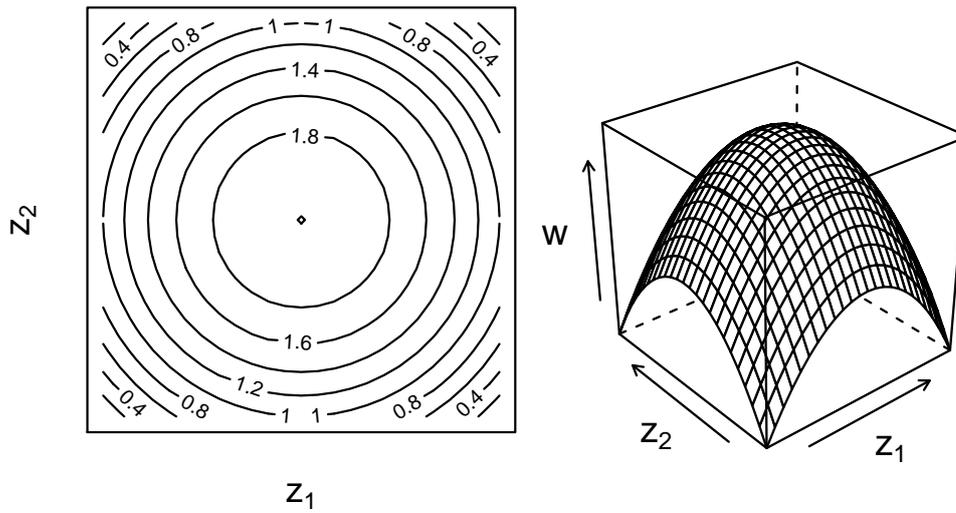
$$\mathbf{G}^{-1}\sigma_a(x, z) = \beta$$

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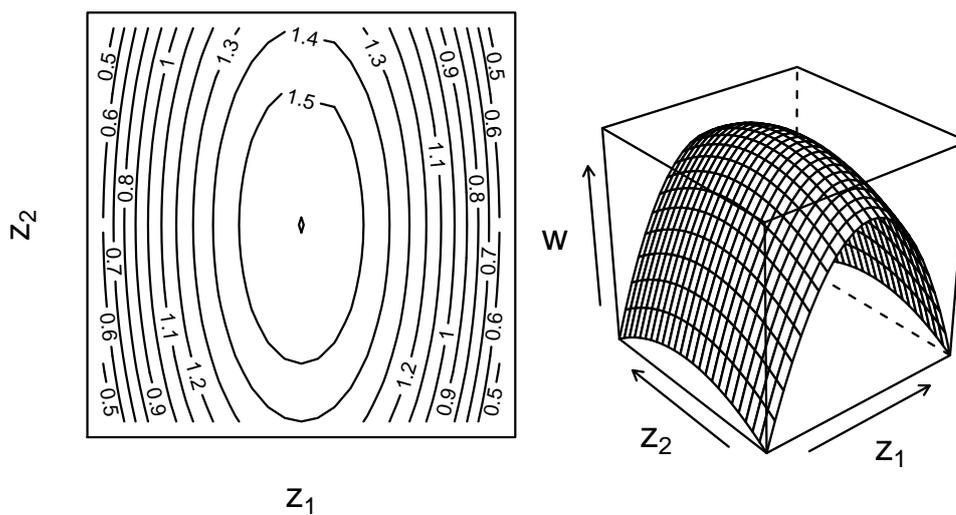
# Non-linear selection, example 1



$$\gamma = \begin{bmatrix} -0.5 & 0 \\ 0 & -0.5 \end{bmatrix}$$

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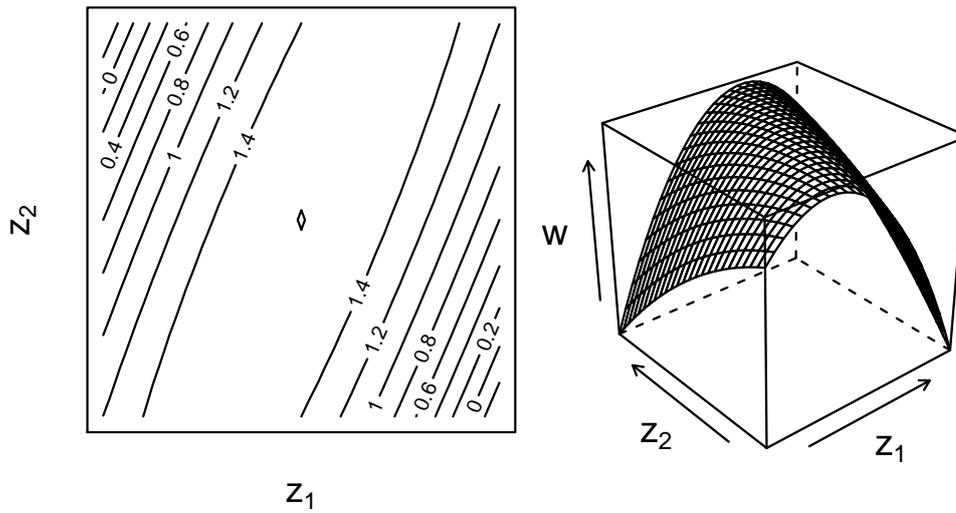
# Non-linear selection, example 2



$$\gamma = \begin{bmatrix} -0.5 & 0 \\ 0 & -0.1 \end{bmatrix}$$

Navigation icons: back, forward, search, etc.

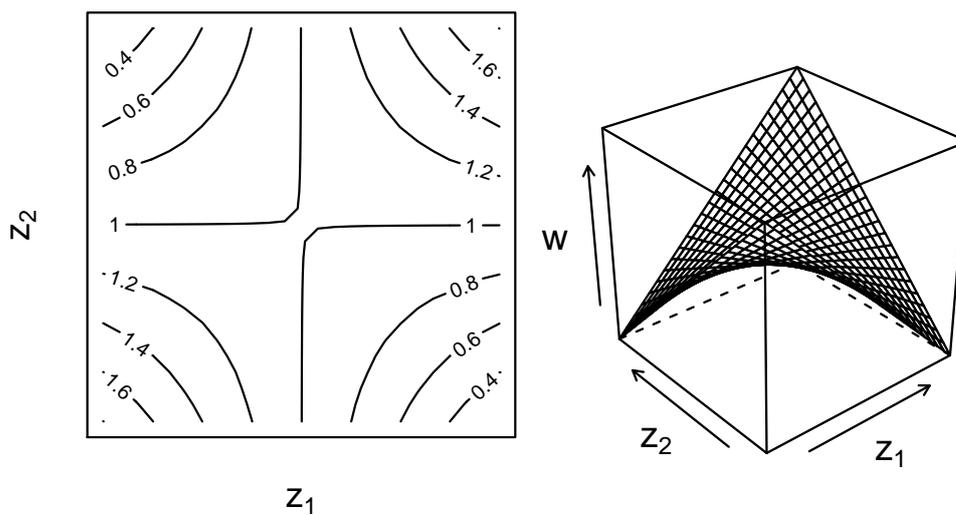
# Non-linear selection, example 3



$$\gamma = \begin{bmatrix} -0.5 & 0.2 \\ 0.2 & -0.1 \end{bmatrix}$$

Navigation icons: back, forward, search, etc.

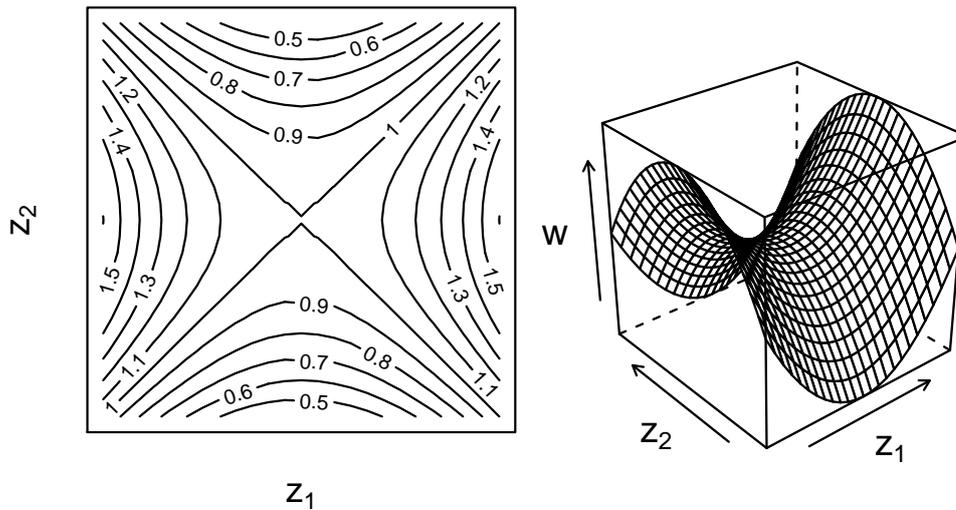
# Non-linear selection, example 4



$$\gamma = \begin{bmatrix} 0 & 0.2 \\ 0.2 & 0 \end{bmatrix}$$

Navigation icons: back, forward, search, etc.

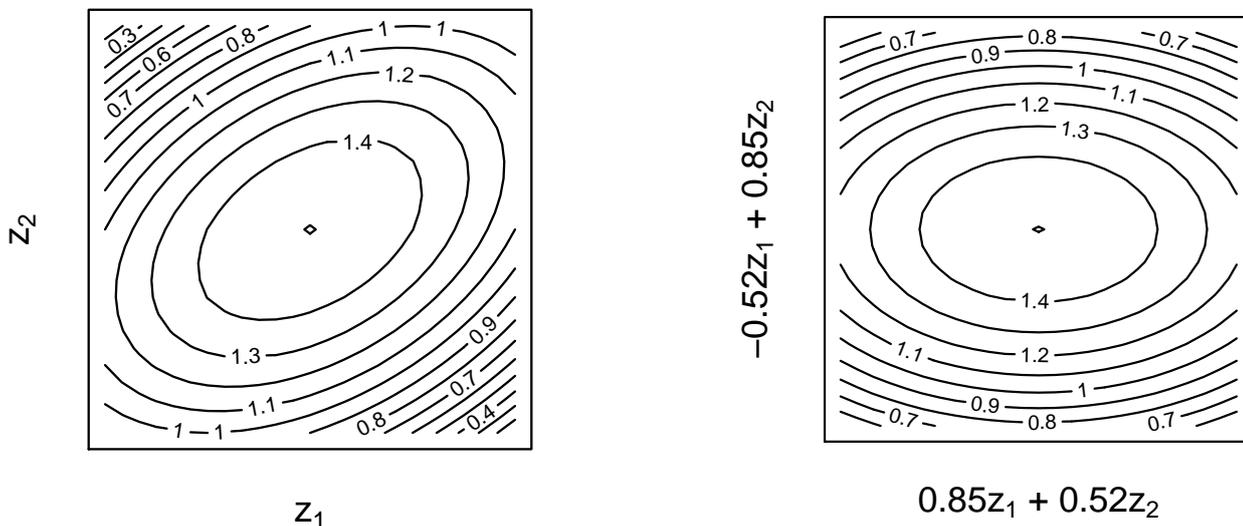
# Non-linear selection, example 5



$$\gamma = \begin{bmatrix} 0.3 & 0 \\ 0 & -0.3 \end{bmatrix}$$

## Major axes of non-linear selection

The  $\gamma$  matrix can be rotated so that it can be described in a new set of axes, which experience no correlational selection.



# Care in inferring the shape of (MV) non-linear selection

- ▶ traits: mass, leg length, horn length
- ▶ variance-standardised analysis

$$\beta = \begin{bmatrix} 0.16 \\ 0.08 \\ -0.12 \end{bmatrix}$$

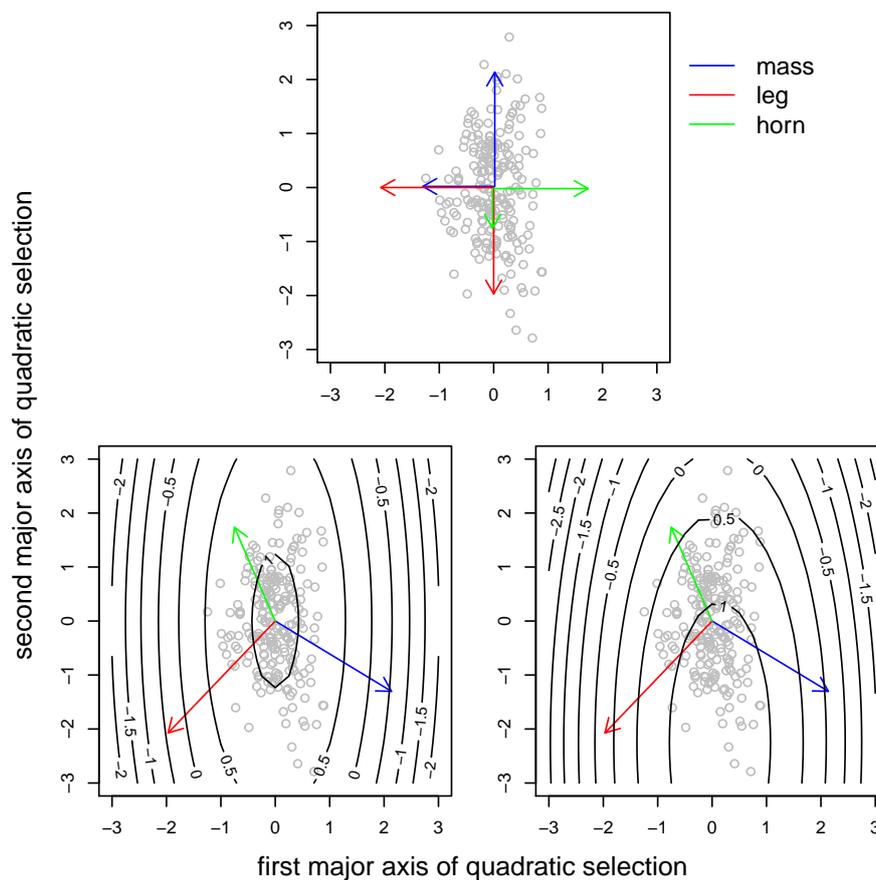
$$\gamma = \begin{bmatrix} -0.35 & 0.30 & 0.15 \\ 0.30 & -0.33 & -0.07 \\ 0.15 & -0.07 & -0.05 \end{bmatrix}$$

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# Care in inferring the shape of (MV) non-linear selection



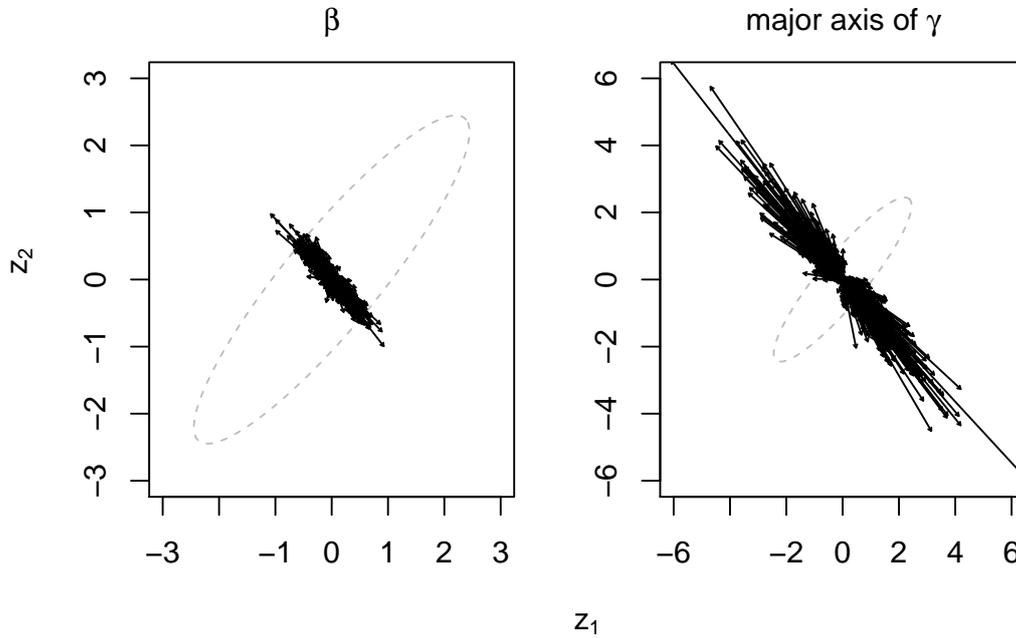
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# Bias in directions of selection relative to axes of phenotype

- ▶ simulated bivariate selection gradient analysis
- ▶ no relationship between trait and fitness

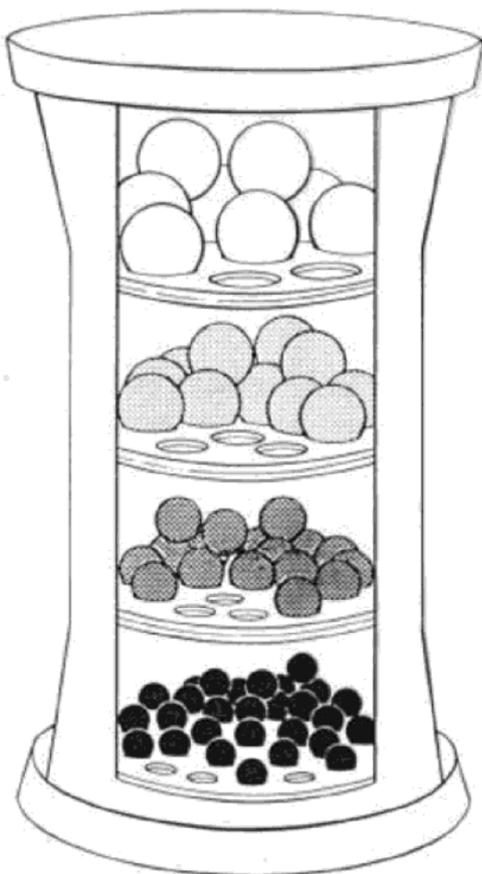


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Does  $\beta$  reflect the relevance of traits to fitness?



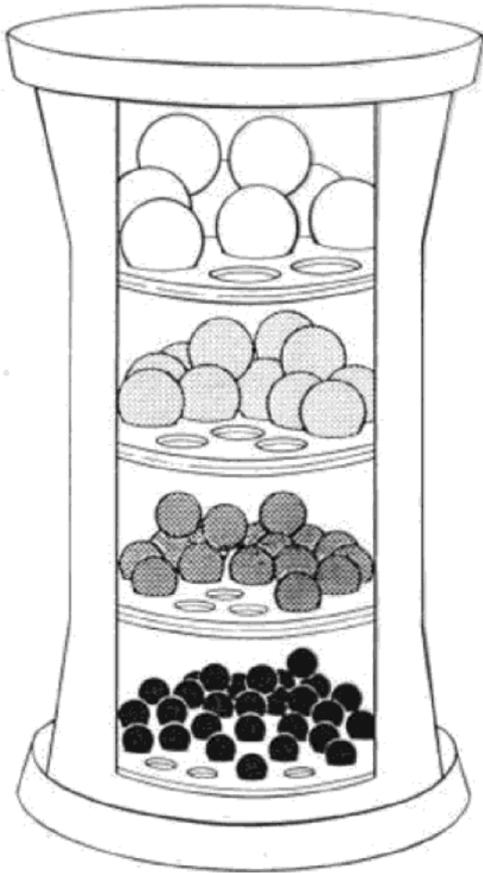
Do black balls make it to the bottom?

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# Does $\beta$ reflect the relevance of traits to fitness?



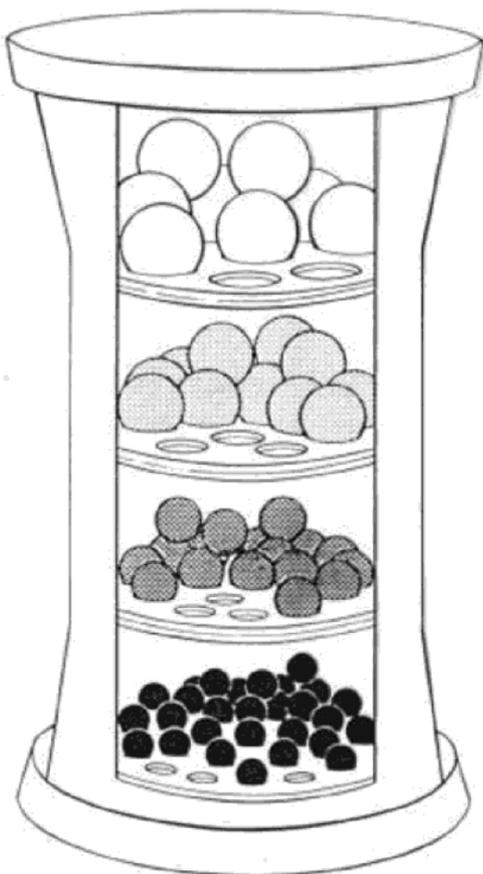
Do black balls make it to the bottom?  
Yes. There is *selection of* black colour



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# Does $\beta$ reflect the relevance of traits to fitness?



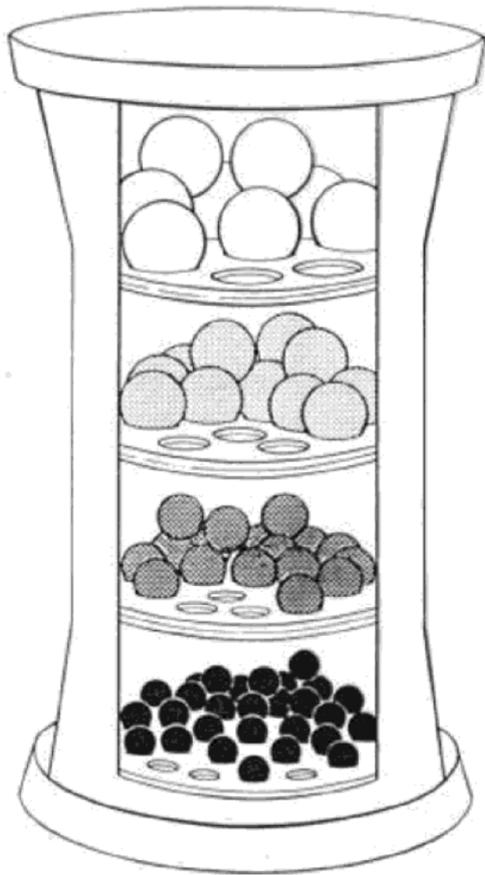
Do black balls make it to the bottom?  
Yes. There is *selection of* black colour; it is *associated* with passage through the toy.



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# Does $\beta$ reflect the relevance of traits to fitness?



Do black balls make it to the bottom?  
Yes. There is *selection of* black colour; it is *associated* with passage through the toy.

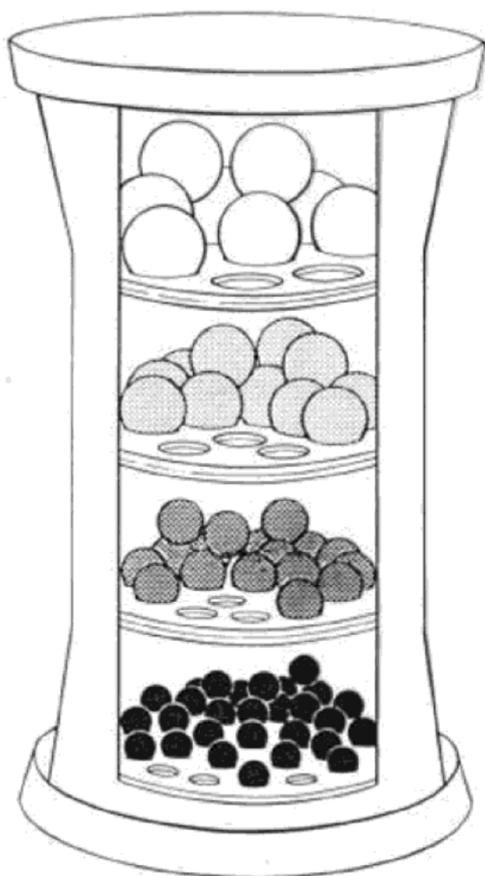
Do does black colour *cause* balls to get to the bottom?



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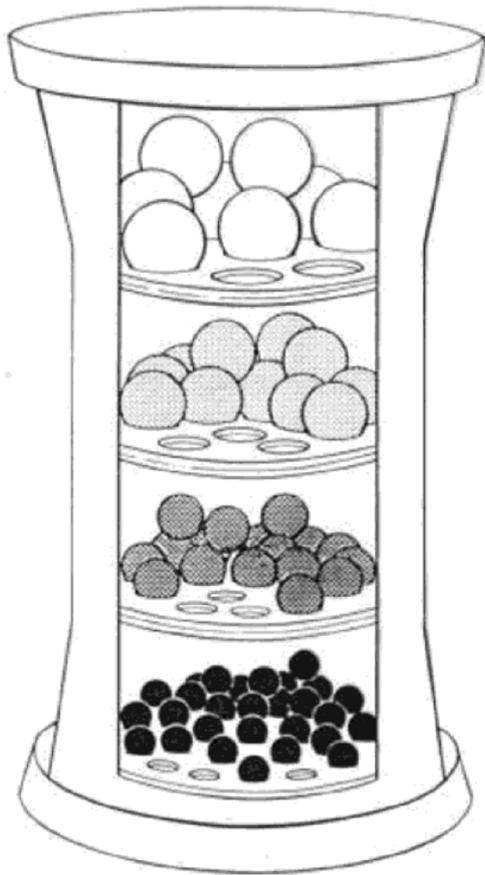
Do does black colour *cause* balls to get to the bottom? No, there is *no selection* for black colour.



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# Does $\beta$ reflect the relevance of traits to fitness?



Do black balls make it to the bottom?  
Yes. There is *selection of* black colour; it is *associated* with passage through the toy.

Does black colour *cause* balls to get to the bottom? No, there is *no selection* for black colour.

$S$  is widely interpreted as representing total selection, something like *selection of*.

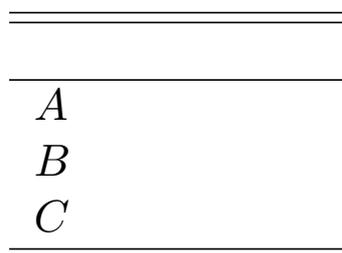
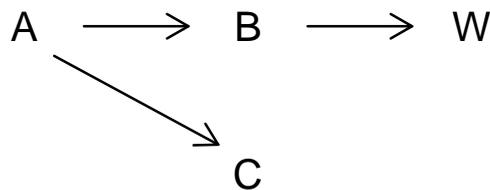
$\beta$  is erroneously interpreted as representing something like *selection for*; however, it is something rather more specific.



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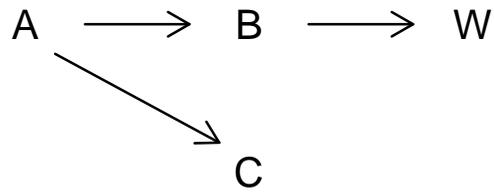
## The $A \rightarrow B \rightarrow W$ toy model



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# The $A \rightarrow B \rightarrow W$ toy model



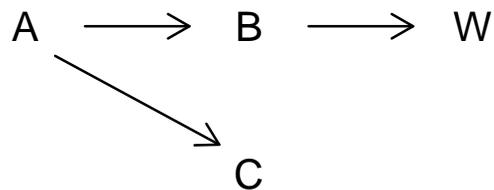
$S$	
$A$	✓
$B$	✓
$C$	✓

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# The $A \rightarrow B \rightarrow W$ toy model



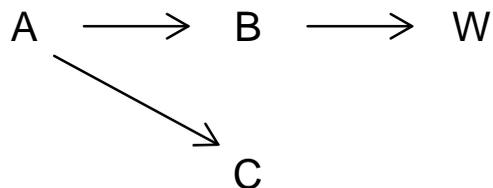
	$S$	$\beta$
$A$	✓	✗
$B$	✓	✓
$C$	✓	✗

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# The $A \rightarrow B \rightarrow W$ toy model



	$S$	$\beta$	$\eta$
$A$	✓	✗	✓
$B$	✓	✓	✓
$C$	✓	✗	✗

## $\eta$ , genetic variation, and evolution 1

- ▶ a Greek letter ( $\eta$ ) does not a selection coefficient make!
- ▶ does  $\eta$  have a role in a  $\Delta\bar{z} = f(\text{genetics}, \text{selection})$  equation?

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- ▶ does  $\eta$  have a role in a  $\Delta\bar{z} = f(\text{genetics}, \text{selection})$  equation?

Total effects of traits on one another are given by

$$\Phi = (\mathbf{I} - \mathbf{b})^{-1}$$

where  $\mathbf{b}$  is a matrix containing a certain arrangement of effects of traits on one another.

It then turns out, if  $\mathbf{G}_\epsilon$  contains genetic variation that is independent of effects in the path model, then

$$\mathbf{G} = \Phi \mathbf{G}_\epsilon \Phi^T$$

and

$$\eta = \Phi^T \beta$$



Key facts from the previous slide:

$$\mathbf{G} = \Phi \mathbf{G}_\epsilon \Phi^T$$

and

$$\eta = \Phi^T \beta$$



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So, from the Lande equation

$$\Delta \bar{\mathbf{z}} = \mathbf{G} \beta$$

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Key facts from the previous slide:

$$\mathbf{G} = \Phi \mathbf{G}_\epsilon \Phi^T$$

and

$$\boldsymbol{\eta} = \Phi^T \boldsymbol{\beta}$$

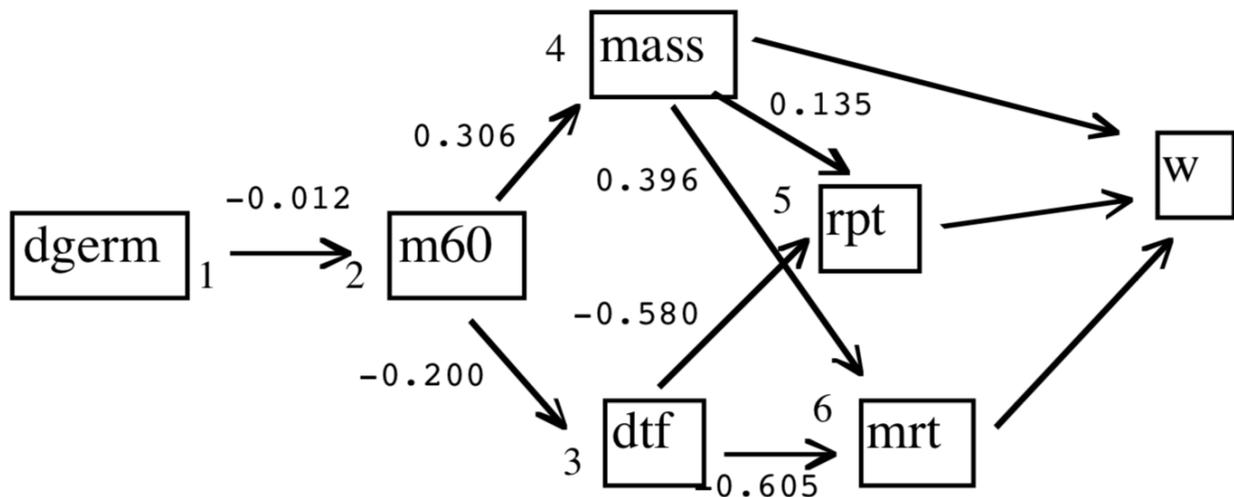
So, from the Lande equation

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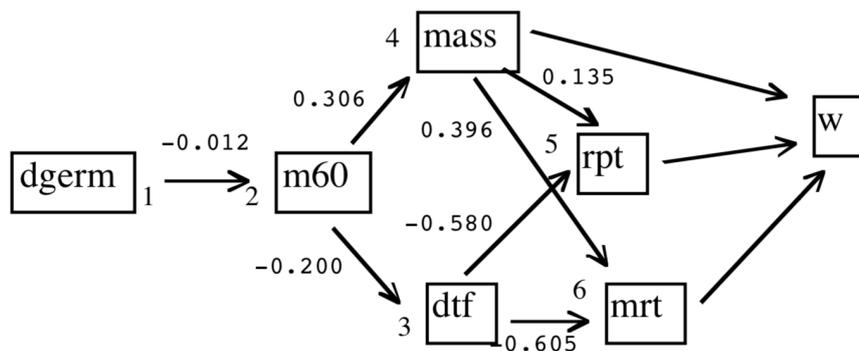
$$\Delta \bar{\mathbf{z}} = \Phi \mathbf{G}_\epsilon \Phi^T \boldsymbol{\beta}$$

$$\Delta \bar{\mathbf{z}} = \Phi \mathbf{G}_\epsilon \boldsymbol{\eta}$$

## Example of estimation of $\eta$



# Example of estimation of $\eta$



$$m60 \sim dgerm$$

$$mass \sim m60$$

$$dtf \sim m60$$

$$rpt \sim mass + dtf$$

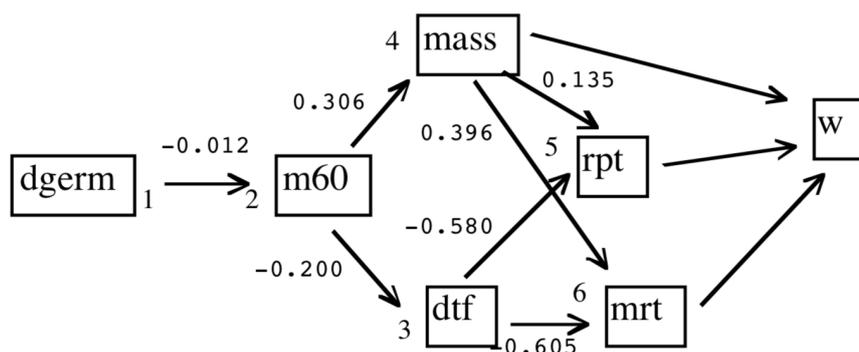
$$mrt \sim mass + dtf$$

$$w \sim mass + rpt + mrt$$

$$\mathbf{b} = \begin{bmatrix} 0 & -0.01 & 0 & 0 & 0 & 0 \\ 0 & 0 & -0.20 & 0.30 & 0 & 0 \\ 0 & 0 & 0 & 0 & -0.58 & -0.60 \\ 0 & 0 & 0 & 0 & 0.13 & 0.39 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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# Example of estimation of $\eta$



$$\mathbf{b} = \begin{bmatrix} 0 & -0.01 & 0 & 0 & 0 & 0 \\ 0 & 0 & -0.20 & 0.30 & 0 & 0 \\ 0 & 0 & 0 & 0 & -0.58 & -0.60 \\ 0 & 0 & 0 & 0 & 0.13 & 0.39 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \boldsymbol{\beta} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ -0.03 \\ 0.15 \\ 0.21 \end{bmatrix}$$

Navigation icons: back, forward, search, etc.

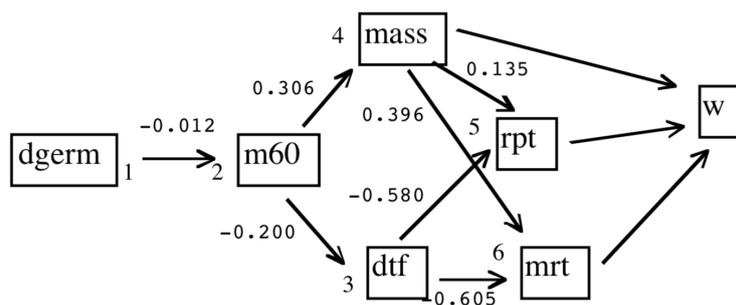
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$$\Phi = (\mathbf{I} - \mathbf{b})^{-1} = \begin{bmatrix} 1 & -0.01 & 0.02 & -0.003 & -0.002 & -0.003 \\ 0 & 1 & -0.20 & 0.30 & 0.157 & 0.242 \\ 0 & 0 & 1 & 0 & -0.580 & -0.605 \\ 0 & 0 & 0 & 1 & 0.135 & 0.396 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

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# Example of estimation of $\eta$



$$\beta_{path} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ -0.0333 \\ 0.157 \\ 0.207 \end{bmatrix}$$

$$\beta_{ols} = \begin{bmatrix} 0.009 \\ 0.004 \\ 0.040 \\ -0.028 \\ 0.142 \\ 0.207 \end{bmatrix}$$

$$\eta = \begin{bmatrix} -0.001 \\ 0.065 \\ -0.216 \\ 0.070 \\ 0.157 \\ 0.207 \end{bmatrix}$$

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